



A Critical Review of Materials Available for Health Monitoring and Control of Offshore Structures

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Overview of Presentation

- ◆ Introduction to classification for smart materials and structures
- ◆ The different materials available
 - Functionality of smart materials
 - Uses of smart materials
 - Advantages and disadvantages of the different materials
- ◆ Conclusion of preferred applications

Smart Materials

- ◆ Materials that function as sensing and/or actuating materials
- ◆ Passively smart materials possess self-repairing or stand-by characteristics
- ◆ Actively smart materials utilize feedback
- ◆ Smart materials reproduce biological functions in load bearing systems

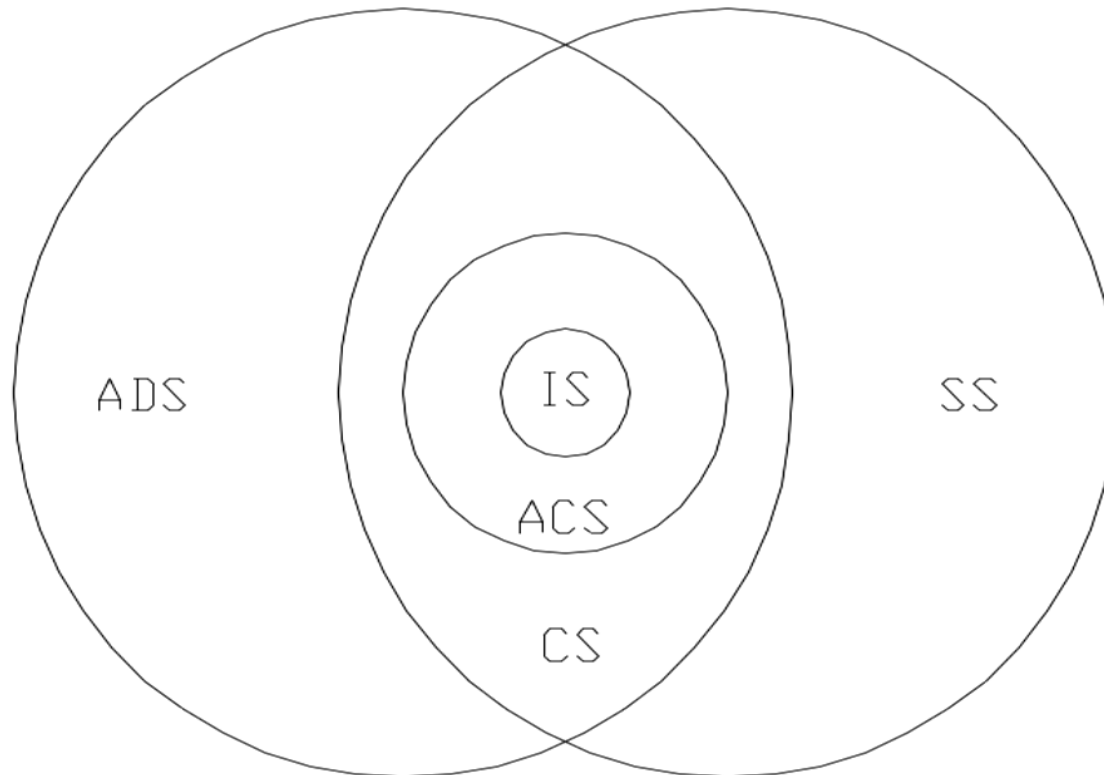


Smart Structures



- ◆ Three criteria in characterizing smart structures
 - A definite purpose
 - Means to achieve that purpose
 - Posses a biological pattern of functionality

Terminologies Used in Field of Smart Structures



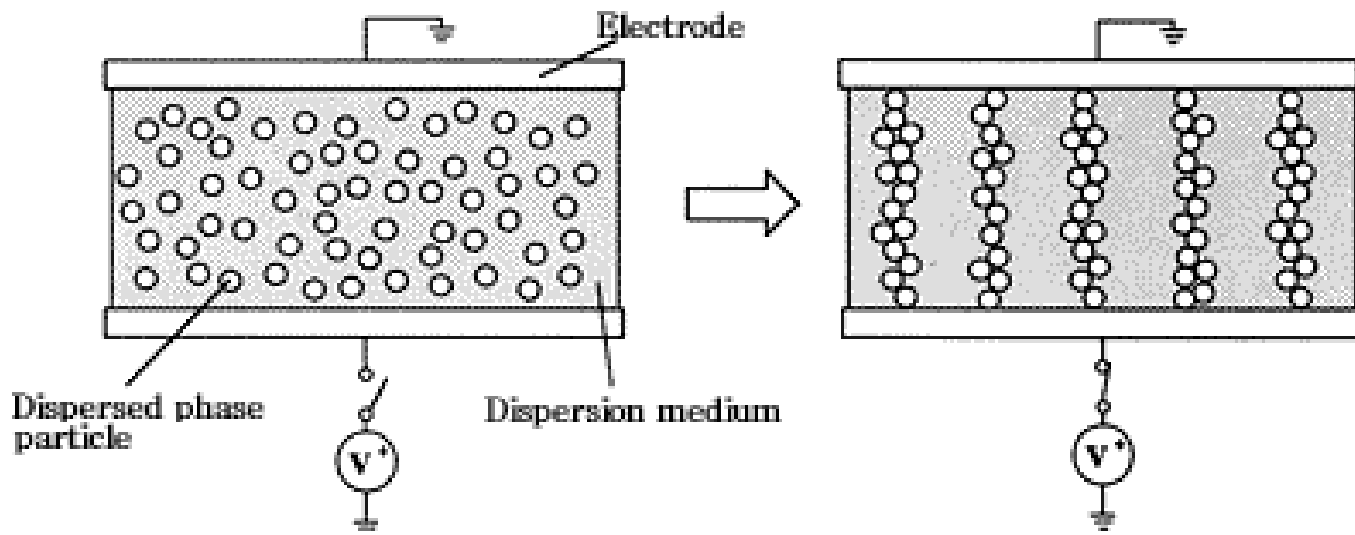
- ◆ ADS = Adaptive Structure, SS = Sensory Structure, CS = Controlled Structure, ACS = Active Structure, IS = Intelligent Structure

Smart Materials Available

- ◆ Actuating Materials
 - Electrorheological Fluids (ER Fluids)
 - Shape Memory Alloys (SMA)
- ◆ Sensing Materials
 - Fiber Optic (F.O.) sensors
- ◆ Dual-Purpose Materials (Actuating & Sensing)
 - Magnetostrictive Materials
 - Piezoelectric Materials

Electrorheological Fluids

- ◆ Consist of dielectric particles submersed in an oily fluid
- ◆ Respond to an electric field by the aligning of dielectric particles

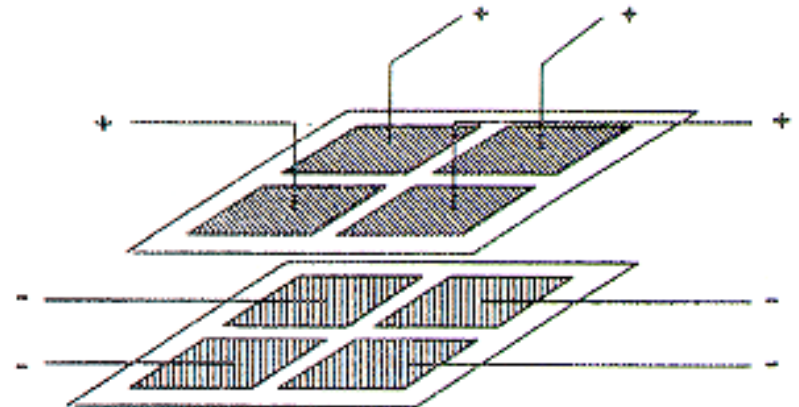
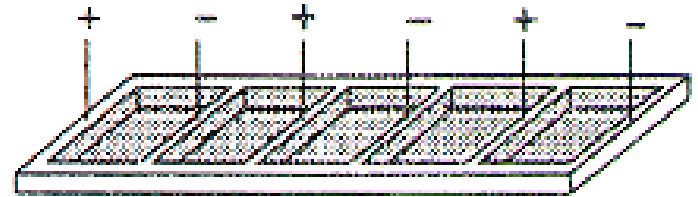
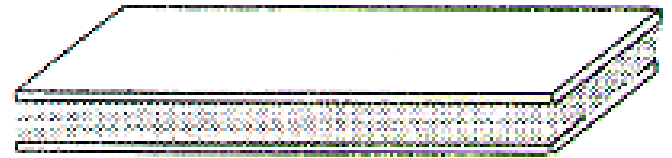


Functionality of ER Fluids

- ◆ Generally used in laminated composite sandwich beam structures
 - Ease of manufacturing
 - Makes addition of ER fluid simple

Common ER Fluid Sandwich Beam Configurations

- ◆ Simple sandwich beam
 - Increased shear properties
- ◆ Compartmentalization
 - Extensional properties
 - Mode shape control





ER Fluid Advantages



- ◆ Quick response (msec)
- ◆ Fairly good structural durability
- ◆ Can operate with both AC and DC voltages
- ◆ Induced shear stress is large

ER Fluid Disadvantages

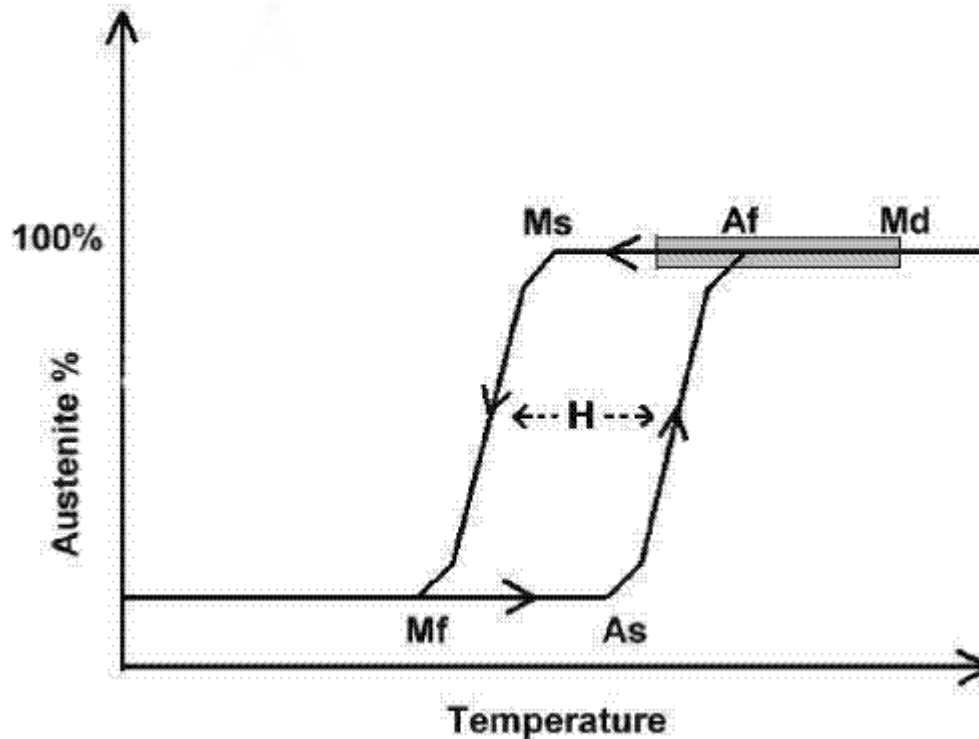
- ◆ Behavior is not well known
- ◆ Poor reproducibility
 - Due to settlement of dielectric particles
- ◆ Produce small forces
 - Requires large amount of material
- ◆ Creep is an issue
- ◆ Strength is relatively low
- ◆ Require large amounts of power

Shape Memory Alloys

- ◆ Respond to an applied electric current by returning to their manufactured shape (Resistive heating)
- ◆ Contain two distinct solid forms
 - Martensite: Low temperature form
 - Austenite: High temperature form
- ◆ Most commonly implemented SMA is Nitinol (Nickel-Titanium Alloy)
 - Due to superior properties compared to other SMA's

Characterization of SMA Behavior

- ◆ SMA's follow a hysteresis loop as follows

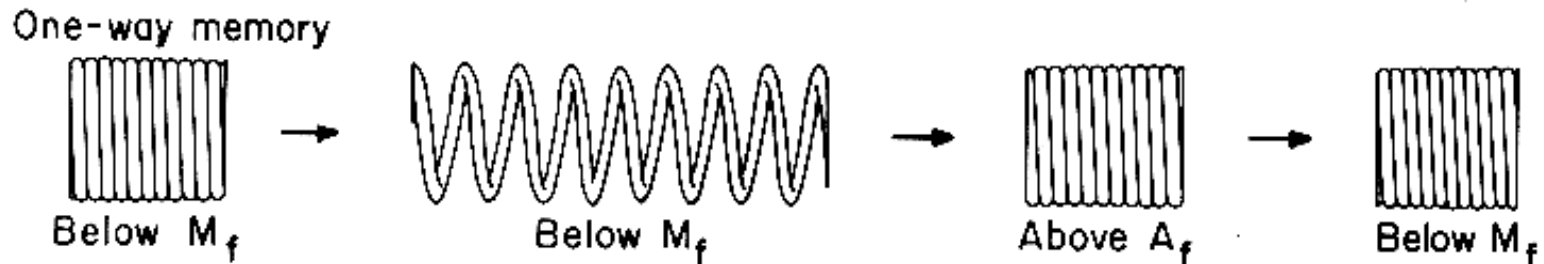


Properties of Nitinol Martensite and Austenite

| | NiTi | |
|---------------------------------|-----------|------------|
| | Austenite | Martensite |
| Ultimate Tensile Strength (MPa) | 800-1500 | 103-1100 |
| Tensile Yield Strength (MPa) | 100-800 | 50-300 |
| Modulus of Elasticity (GPa) | 70-110 | 21-69 |
| Elongation at Failure (%) | 1-20 | Up to 60 |

Functionality of SMA

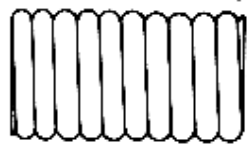
- ◆ Functionality depends on manufacturing process and operation temperature
 - Three functional methods
- ◆ One-way Shape Memory



Functionality of SMA

◆ Two-Way Shape Memory

Two-way memory



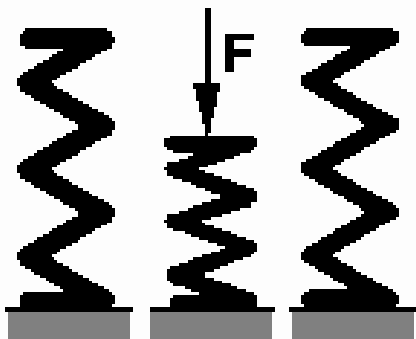
Below M_f



Above A_f

◆ Superelastic Effect

$T > A_f$ $T > A_f$ $T > A_f$



SMA Transformation Strain Capabilities

| Number of Cycles | Transformation Strain |
|------------------|-----------------------|
| Up to 1 | Up to 8% |
| 1-100 | Up to 5% |
| 100-10,000 | Up to 3% |
| 10,000-100,000 | Max 2% |

SMA Advantages

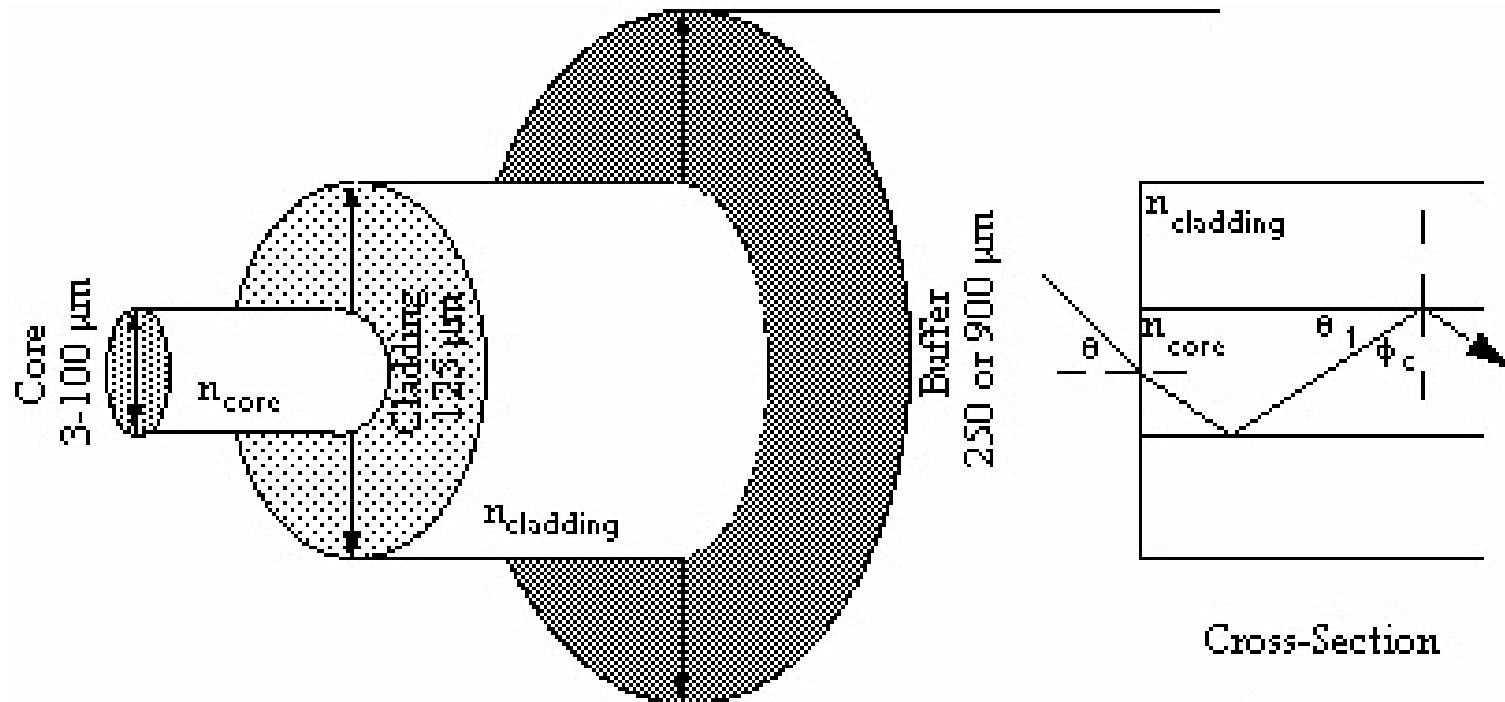
- ◆ Produce very large recovery stresses
- ◆ Easily machined into different shapes and sizes
- ◆ Manufactured to desired properties
 - Mechanical and transition temperatures
- ◆ Material is ductile
- ◆ Very effective for low frequency vibrations
 - (< 5 Hz.)
- ◆ Heating is easily done with resistive heating
- ◆ Easily embedded into laminated composites

SMA Disadvantages

- ◆ Slow reaction time
 - Ineffective at higher frequency ranges
- ◆ Low energy efficiency conversion
- ◆ May not be able to operate in conditions with large temperature ranges
- ◆ Unweldable and expensive for large scale projects
- ◆ Non-linear thermomechanical behavior can limit the accuracy

Fiber Optic Sensors

- ◆ Typical fiber optic is constructed as follows



Classification of Fiber Optic Sensors

- ◆ Four methods of classification
 - Type of media transmitted
 - Mode of the fiber
 - Measured parameter
 - Location of sensing element

Fiber Optic Media Measurement Methods

- ◆ Light Intensity
 - Intensiometric sensor
- ◆ Phase Change
 - Interferometric sensor
- ◆ Frequency Change
 - Polarimetric sensor
- ◆ Polarization
 - Modalmetric sensor

Fiber Optic Modes of Measurement

- ◆ Single Mode Fibers
 - Light is transmitted directly down the fiber without refraction between core and cladding
- ◆ Multimode Fibers
 - Light is refracted between core and cladding

Sensing Parameter of Sensor

- ◆ Physical Sensor
 - Stress, temperature etc.
- ◆ Chemical Sensor
 - pH, gas composition, etc.
- ◆ Bio-medical Sensor
 - Blood flow, glucose content, etc.

Location of Sensing Element

- ◆ Extrinsic
 - Sensing is done outside fiber optic cable
 - Fiber only acts as a data conduit
- ◆ Intrinsic
 - Physical properties of the fiber are changed

Fiber Optic Advantages

- ◆ Small size and light weight
- ◆ High sensitivity
- ◆ Corrosion resistant
- ◆ Wide frequency bandwidth
- ◆ Simultaneous sensing of numerous parameters
- ◆ High tensile strength and fatigue life
- ◆ Quick response
- ◆ Immune to electromagnetic interference

Fiber Optic Disadvantages

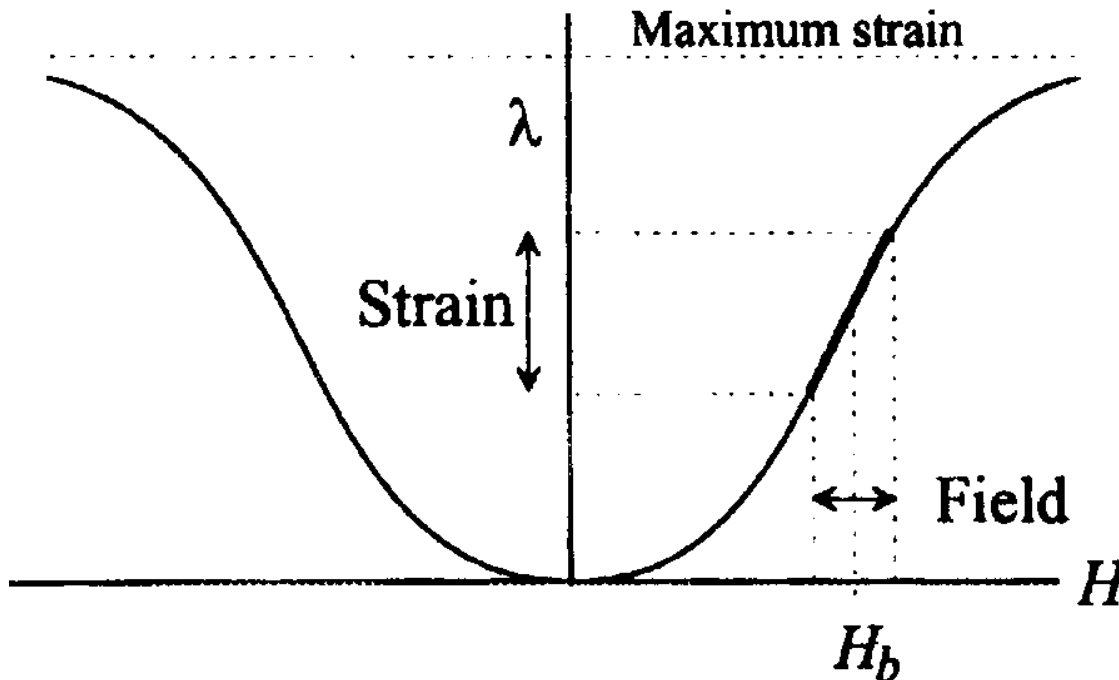
- ◆ May need to isolate from unwanted parameters
- ◆ Availability of optical sources
- ◆ Cost and availability of instrumentation
- ◆ Long term stability is relatively unknown
- ◆ Low awareness of fiber optic sensor technology

Magnetostrictives

- ◆ Implemented as an actuator with an applied magnetic field
 - Magnetic field is generally created by running a current through wire loop
- ◆ Used as a sensor by producing a magnetic field when strained

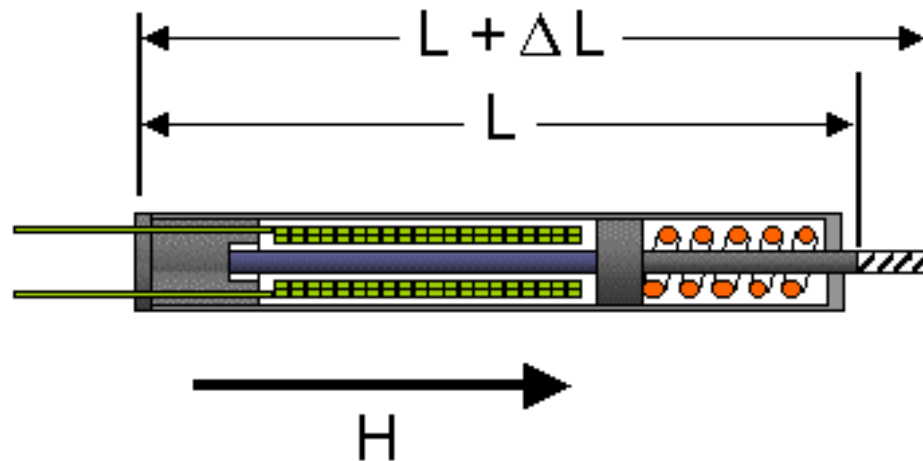
Magnetostrictive Behavior

- ◆ Behavior follows the following curve



Magnetostrictive Functionality

- ◆ Generally implemented as a linear actuator



- ◆ Displacement is independent of the applied field direction
 - Depends on material

Magnetostrictive Advantages

- ◆ Fast response time (μsec)
- ◆ High Curie temperature
- ◆ Relatively high strain and force capabilities compared to piezoelectrics
- ◆ No aging effects
- ◆ Operate over large temperature range
- ◆ Low voltage operation

Magnetostrictive Disadvantages

- ◆ Low tensile strengths
- ◆ Brittle
- ◆ Costly due to rare earth metals involved
- ◆ Large magnetic field required
- ◆ Equipment intensive
 - In order to produce magnetic field

Piezoelectric Materials

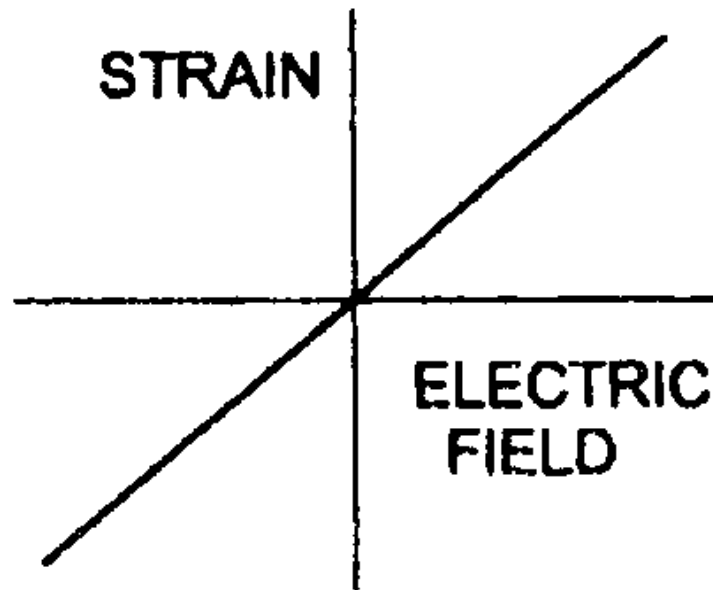
- ◆ Operate as actuator with an electric field applied causing displacements
- ◆ Operate as sensor by producing an electric field when strained
- ◆ Classified based on polarized direction and resulting displacement directions

Piezoelectric Classification

- ◆ Three directions are generally considered
 - 33-Mode: Polarized through thickness and displaces in the thickness direction
 - 31-Mode: Polarized through thickness and displaces in the longitudinal direction
 - 15-Mode: Polarized in longitudinal direction and displaces in shear

Piezoelectric Behavior

- ◆ Behave in a linear fashion
 - Resulting strain is directly proportional to applied field

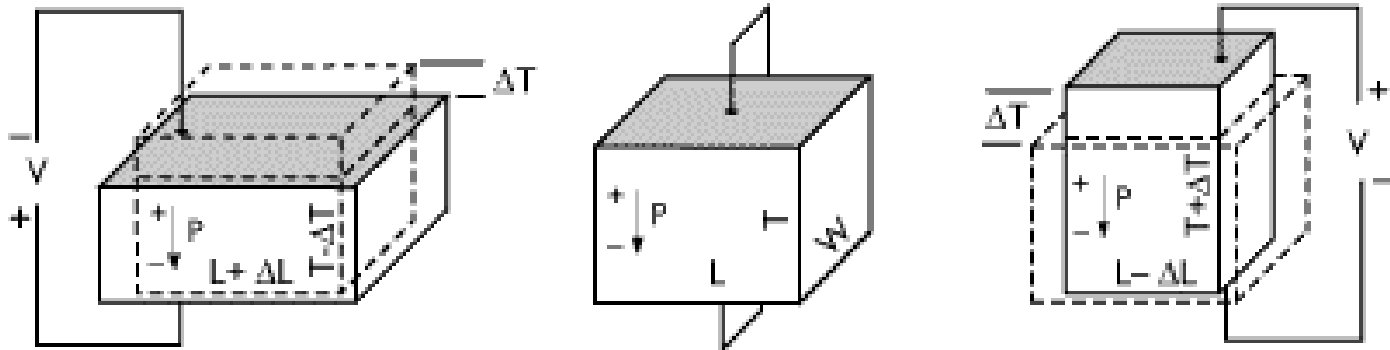


Piezoelectric Functionality

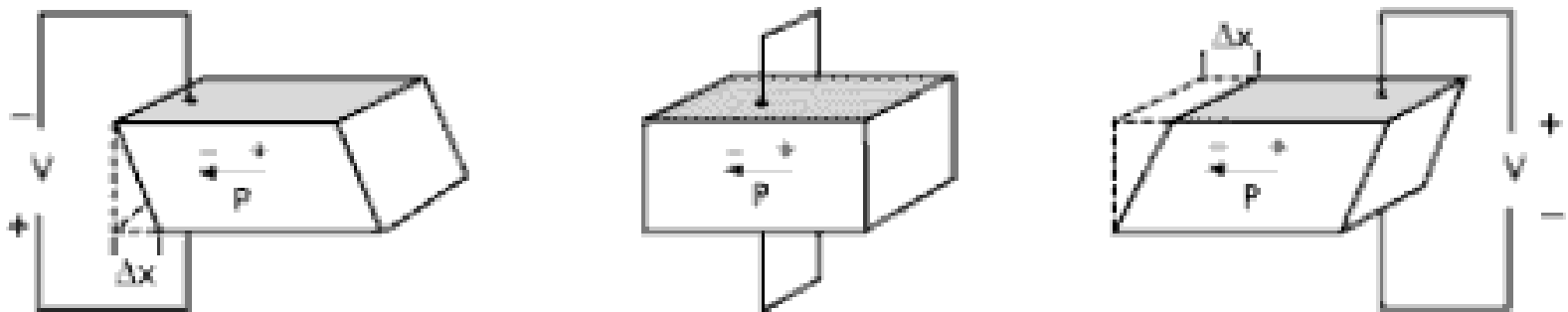
- ◆ Three typical actuator modes
 - Expansion/Contraction
 - Utilizes 33-mode and 31-mode properties
 - Shear
 - Utilizes 15-mode properties
 - Bending
 - Utilizes 31-mode properties

Piezoelectric Functionality

◆ Expansion/Contraction Actuator

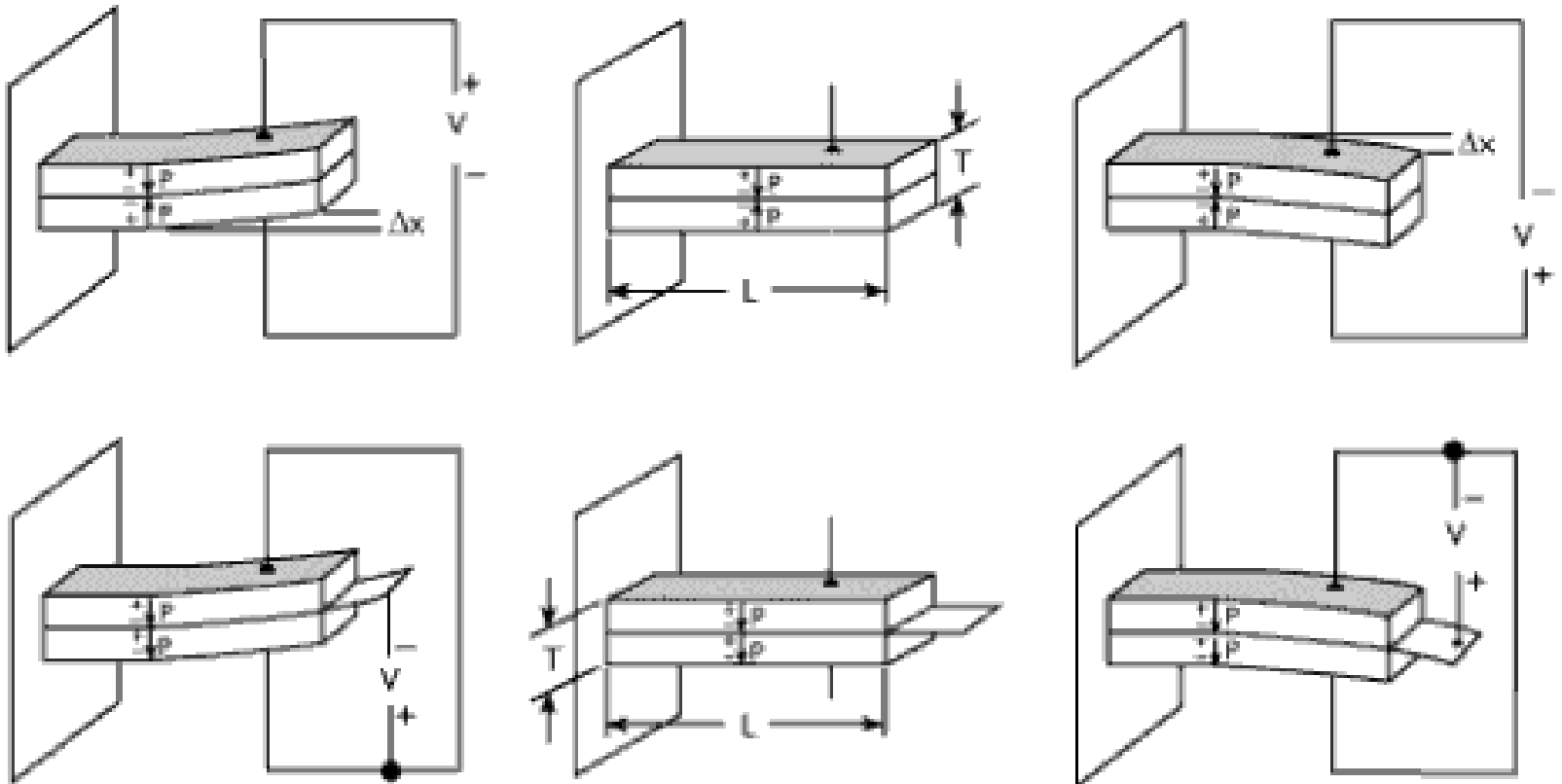


◆ Shear Actuator



Piezoelectric Functionality

- ◆ Bending Actuator: Series or parallel connection



Piezoelectric Advantages

- ◆ Compact and light weight
- ◆ Displacement proportional to applied voltage
- ◆ Operate over large temperature range
- ◆ Fast response to applied voltage (msec)
- ◆ Repeatable sub-nanometer steps at high frequency
- ◆ No moving parts
 - No wear and tear on the element
- ◆ Function at high frequencies
- ◆ Excellent stability
- ◆ Easily embedded into laminated composites

Piezoelectric Disadvantages

- ◆ Brittle due to crystalline structure
- ◆ Produce small strains compared to SMA and magnetostrictives
- ◆ Cannot withstand high shear and tension
- ◆ Material does age
- ◆ Uses active control
 - Can lead to instability
- ◆ Can become depolarized
 - High voltages, high temperatures, large stresses

Conclusion

- ◆ Piezoelectrics and magnetostrictives are most effective for high frequency control applications
 - Piezoelectrics for applications where size of the element is of concern
 - Magnetostrictives are good when size is of no concern
- ◆ Shape memory alloys are very effective for low frequency vibration or shape control
- ◆ Electrorheological fluids are still being explored
 - Sandwich beams are generally the only structural application
- ◆ Fiber optic sensors are very effective in all applications



Questions
